

DDA4210/MAIR6002 Advanced Machine Learning

Lecture 05-I Graph Cut and Spectral Clustering

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Overview

- 1 Introduction
- 2 Graph Partition
- 3 Minimum Cut and Normalized Cut
- 4 Spectral Clustering Algorithm

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- 2 Graph Partition
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Unsupervised Learning

- Supervised learning
 - Use labeled data pairs $\{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^N$ to learn a function $\mathbf{y} = f(\mathbf{x})$.
- Unsupervised learning
 - Learn something useful from unlabeled data $\{\mathbf{x}_i\}_{i=1}^N$.

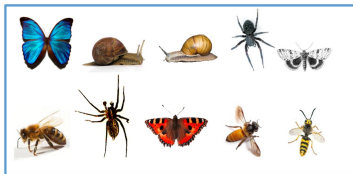
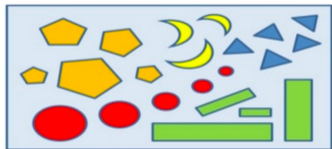
Clustering

- Clustering

$\{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4, \mathbf{x}_5, \mathbf{x}_6, \mathbf{x}_7, \mathbf{x}_8, \mathbf{x}_9, \mathbf{x}_{10}\}$

$\{\mathbf{x}_1, \mathbf{x}_3, \mathbf{x}_8\}$ $\{\mathbf{x}_2, \mathbf{x}_4, \mathbf{x}_5, \mathbf{x}_{10}\}$ $\{\mathbf{x}_6, \mathbf{x}_7, \mathbf{x}_9\}$

- Unsupervised grouping of datapoints.
 - Knowledge discovery.
 - Useful when don't know what you're looking for.
- Basic idea of clustering
 - Group together similar instances.



- Hierarchical clustering (intuitive, not included in this course)
- K-means clustering (learned in basic ML courses)
- Mixture of Gaussians (learned in basic ML courses)
- **Spectral clustering**
- Subspace clustering (not included in this course)
- Deep learning based clustering (not included in this course)

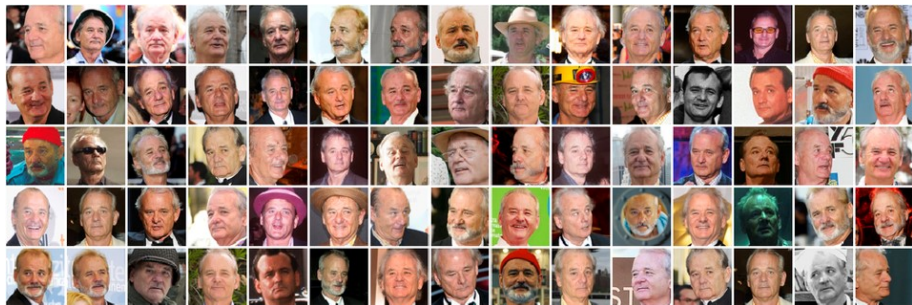
Applications of Clustering

- Image segmentation
 - Break up image into meaningful or perceptually similar regions.



Applications of Clustering

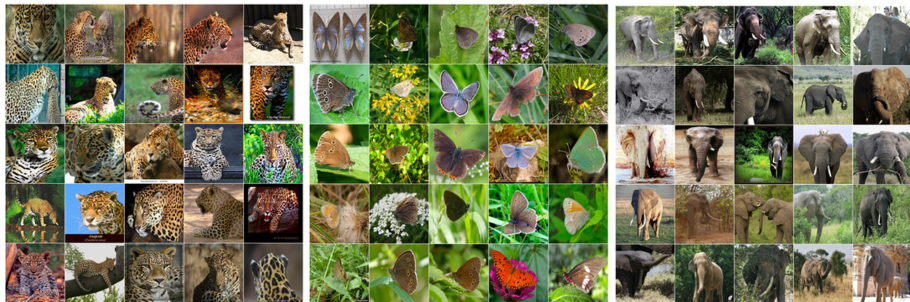
- Image clustering



Difficult!

Applications of Clustering

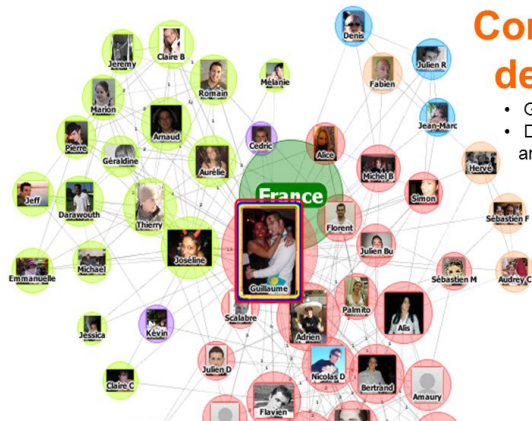
- Image clustering



Very difficult!

Applications of Clustering

- Gene and cell clustering
- Document clustering
- Recommendation system (How to do?)
- Social network analysis
- Community detection

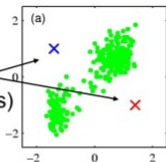


Community detection

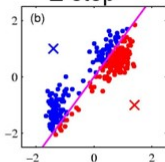
- Global structure
- Distribution of actors and activities

K-Means Clustering: Example

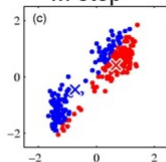
Initial
Choice of
Means
(Parameters)



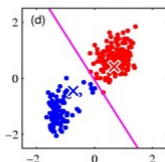
E step



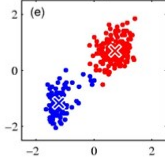
M step



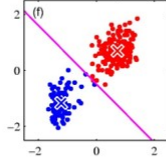
E step



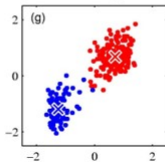
M step



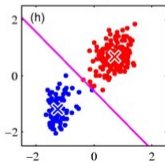
E step



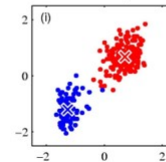
M step



E step



M step

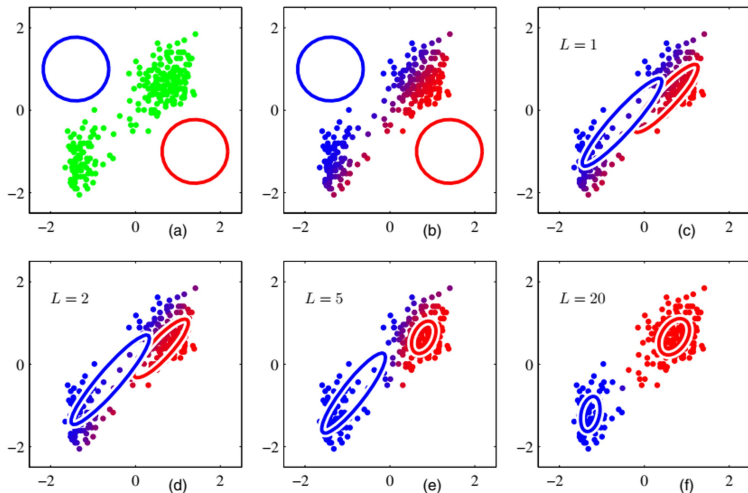


E step:
parameters
are fixed
Distributions
are
optimized

M step:
distributions
are fixed
Parameters
are
optimized

← Final
Clusters
And
Means

GMM: Example

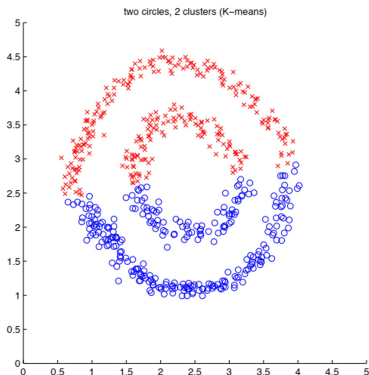


L: cycles of EM

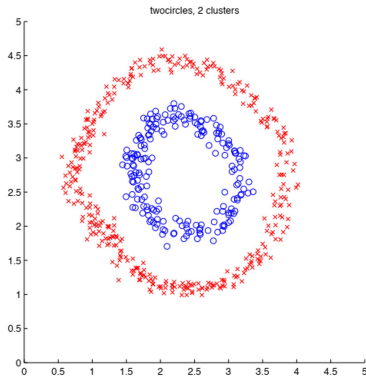
This is the Old Faithful Geyser dataset [PRML, Bishop]

Main Limitation of K-means

K-means

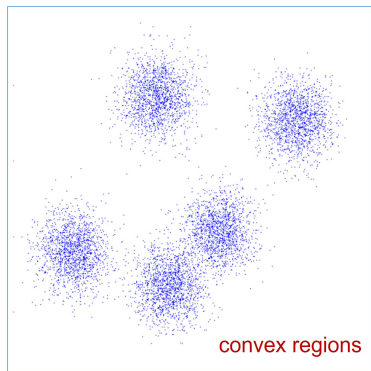


Spectral clustering

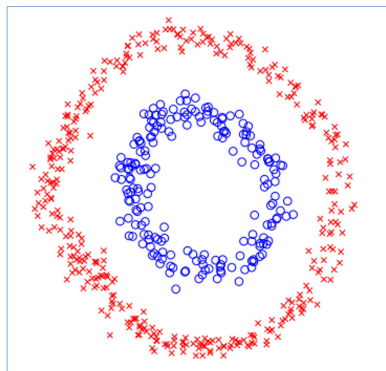


Clustering Criterion

- Two different clustering criteria
 - Compactness, e.g., k-means, Gaussian mixture models
 - Connectivity, e.g., spectral clustering



Compactness



Connectivity

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Graph Partition

Similarity Graph: $G(V,E,W)$

V – Vertices (Data points)

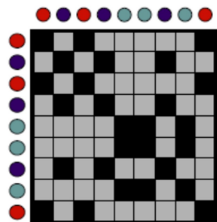
E – Edge if similarity > 0

W - Edge weights (similarities)

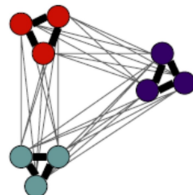
affinity matrix



Data



Similarities



Similarity graph

$$V = \{v_1, v_2, \dots, v_N\}, \quad E = \{e_1, e_2, \dots, e_l\}, \quad W = \begin{bmatrix} & & & & & & & & & & \\ & & & & & & & & & & \\ \dots & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \end{bmatrix}$$

W is usually nonnegative and symmetric, and $w_{ij} = 0$.

Graph Partition

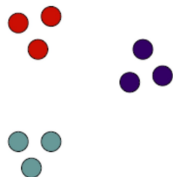
Similarity Graph: $G(V,E,W)$

V – Vertices (Data points)

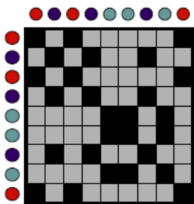
E – Edge if similarity > 0

W - Edge weights (similarities)

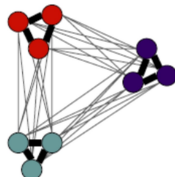
affinity matrix



Data



Similarities

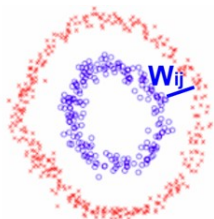


Similarity graph

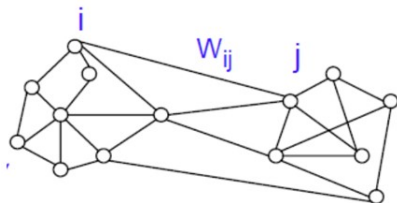
- Similarity graph
 - Model local neighborhood relations between data points
 - Exist naturally or need to be constructed
- **Graph partition:** Partition the graph so that edges within a group have large weights and edges across groups have small weights.

Similarity Graph Construction

Given $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N$, construct a similarity graph.



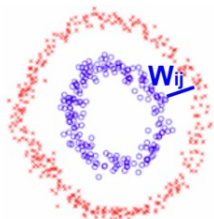
Data clustering



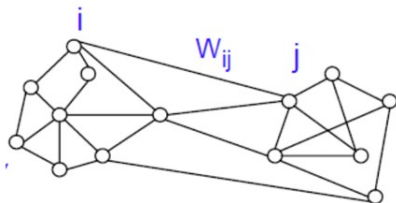
$G = \{V, E\}$

Similarity Graph Construction

Given $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N$, construct a similarity graph.



Data clustering



$G = \{V, E\}$

- k -nearest neighbor graph
- ϵ -neighborhood graph
- Gaussian kernel similarity function

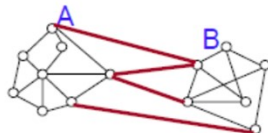
$$k(\mathbf{x}_i, \mathbf{x}_j) = \exp\left(-\frac{\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2}\right)$$

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Minimum Cut

Minimum cut: Partition graph into two sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum.

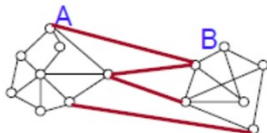
$$\text{cut}(A, B) := \sum_{i \in A, j \in B} w_{ij}$$



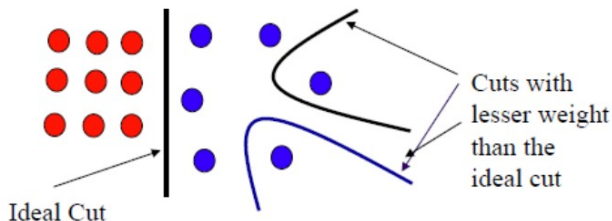
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Minimum cut: Partition graph into two sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum.

$$\text{cut}(A, B) := \sum_{i \in A, j \in B} w_{ij}$$



- Easy to solve $O(|V||E|)$ algorithm
- Not satisfactory partition? Often isolates vertices



Normalized Cut

Normalized cut: Partition graph into two sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum & sizes of A and B are very similar.

Let $\text{vol}(A) = \sum_{i \in A} d_i$, where $d_i = \sum_{j=1}^N w_{ij}$. Define the objective function as

$$\text{Ncut}(A, B) := \text{cut}(A, B) \left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)} \right)$$

Normalized Cut

Normalized cut: Partition graph into two sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum & sizes of A and B are very similar.

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- Ncut is NP-hard to solve
- Spectral clustering is a relaxation

Degree Matrix and Graph Laplacian

- Given a graph with similarity matrix

$$\mathbf{W} = \begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1N} \\ w_{21} & w_{22} & \cdots & w_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ w_{N1} & w_{N2} & \cdots & w_{NN} \end{bmatrix}$$

- The degree matrix of the graph is defined as

$$\mathbf{D} = \begin{bmatrix} d_1 & 0 & \cdots & 0 \\ 0 & d_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & d_N \end{bmatrix}$$

where $d_j = \sum_{i=1}^N w_{ij}$. d_j is the degree of vertex j of the graph.

- The graph Laplacian matrix is defined as $\mathbf{L} = \mathbf{D} - \mathbf{W}$

Normalized Cut and Graph Laplacian (optional)

Recall $\mathbf{L} = \mathbf{D} - \mathbf{W}$ and $\mathbf{D} = \text{diag}(d_1, \dots, d_N)$

$$\text{Let } \mathbf{u} = [u_1, u_2, \dots, u_N]^T \quad \text{with } u_i = \begin{cases} \frac{1}{\text{vol}(A)}, & \text{if } i \in A \\ -\frac{1}{\text{vol}(B)}, & \text{if } i \in B \end{cases}$$

$$\mathbf{u}^T \mathbf{L} \mathbf{u} = \frac{1}{2} \sum_{ij} w_{ij} (u_i - u_j)^2 = \sum_{i \in A, j \in B} w_{ij} \left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)} \right)^2$$

$$\mathbf{u}^T \mathbf{D} \mathbf{u} = \sum_i d_i u_i^2 = \sum_{i \in A} \frac{d_i}{\text{vol}(A)^2} + \sum_{j \in B} \frac{d_j}{\text{vol}(B)^2} = \frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)}$$

Normalized Cut and Graph Laplacian (optional)

Recall $\mathbf{L} = \mathbf{D} - \mathbf{W}$ and $\mathbf{D} = \text{diag}(d_1, \dots, d_N)$

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Then we have

$$\frac{\mathbf{u}^T \mathbf{L} \mathbf{u}}{\mathbf{u}^T \mathbf{D} \mathbf{u}} = \sum_{i \in A, j \in B} w_{ij} \left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)} \right) = \text{Ncut}(A, B)$$

Normalized Cut and Graph Laplacian

Ncut is equivalent to the minimization of $\frac{\mathbf{u}^\top \mathbf{L} \mathbf{u}}{\mathbf{u}^\top \mathbf{D} \mathbf{u}}$, i.e.,

$$\min_{A,B} \text{Ncut}(A, B) \iff \min_{\mathbf{u}} \frac{\mathbf{u}^\top \mathbf{L} \mathbf{u}}{\mathbf{u}^\top \mathbf{D} \mathbf{u}}, \quad \mathbf{u} \in \mathbb{R}^N, \quad u_i = \begin{cases} \frac{1}{\text{vol}(A)}, & \text{if } i \in A \\ -\frac{1}{\text{vol}(B)}, & \text{if } i \in B \end{cases}$$

¹Detailed derivation can be found in: *Shi and Malik. Normalized Cuts and Image Segmentation. 2000.*

Normalized Cut and Graph Laplacian

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Equivalent to¹: $\min_{\mathbf{u}} \frac{\mathbf{u}^T \mathbf{L} \mathbf{u}}{\mathbf{u}^T \mathbf{D} \mathbf{u}} \quad \text{s.t.} \quad \mathbf{u}^T \mathbf{D} \mathbf{1} = 0, \quad u_i \in \{1, -b\}$

* b is some positive constant.

Relaxation: \mathbf{u} –second eigenvector of generalized eigenvalue problem

$$\mathbf{L} \mathbf{u} = \lambda \mathbf{D} \mathbf{u}$$

Obtain cluster assignments by thresholding \mathbf{u} at 0

¹Detailed derivation can be found in: *Shi and Malik. Normalized Cuts and Image Segmentation. 2000.*

Normalized Cut and Graph Laplacian

$$\min_{A,B} \text{Ncut}(A, B) \iff \min_{\mathbf{u}} \frac{\mathbf{u}^\top \mathbf{L} \mathbf{u}}{\mathbf{u}^\top \mathbf{D} \mathbf{u}} \quad \text{s.t. } \mathbf{u}^\top \mathbf{D} \mathbf{1} = \mathbf{0}, u_i \in \{1, -b\}$$

- Relaxation: Let \mathbf{u} be the eigenvector corresponding to the second smallest eigenvalue of the generalized eigenvalue problem

$$\mathbf{L} \mathbf{u} = \lambda \mathbf{D} \mathbf{u}$$

- Equivalent to eigenvector corresponding to the second smallest eigenvalue of the normalized Laplacian

$$\tilde{\mathbf{L}} = \mathbf{D}^{-1} \mathbf{L} = \mathbf{I} - \mathbf{D}^{-1} \mathbf{W}$$

Normalized Cut and Graph Laplacian

$$\min_{A,B} \text{Ncut}(A, B) \iff \min_{\mathbf{u}} \frac{\mathbf{u}^\top \mathbf{L} \mathbf{u}}{\mathbf{u}^\top \mathbf{D} \mathbf{u}} \quad \text{s.t. } \mathbf{u}^\top \mathbf{D} \mathbf{1} = 0, u_i \in \{1, -b\}$$

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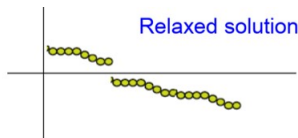
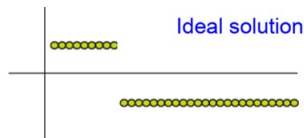
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- Equivalent to eigenvector corresponding to the second smallest eigenvalue of the normalized Laplacian

$$\tilde{\mathbf{L}} = \mathbf{D}^{-1} \mathbf{L} = \mathbf{I} - \mathbf{D}^{-1} \mathbf{W}$$

- Obtain binary partition as follows:

$$i \in A \text{ if } u_i \geq 0, \quad i \in B \text{ if } u_i < 0$$



- It can be extended to multiple clusters \rightarrow Spectral Clustering

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Spectral Clustering Algorithm

Input: data $\mathbf{X} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N\}$, number K of clusters

- **Step 1.** Construct a similarity matrix \mathbf{W}

e.g. use $w_{ij} = \exp\left(-\frac{\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2}\right)$

k -nearest neighbor graph, or ϵ -neighborhood graph

- **Step 2.** Compute the Laplacian matrix \mathbf{L} (or normalized \mathbf{L})

- $\mathbf{L} = \mathbf{D} - \mathbf{W}$

- $\tilde{\mathbf{L}} = \mathbf{I} - \mathbf{D}^{-1}\mathbf{W}$ (normalized)

- $\hat{\mathbf{L}} = \mathbf{I} - \mathbf{D}^{-1/2}\mathbf{W}\mathbf{D}^{-1/2}$ (symmetric normalized, recommended)

Spectral Clustering Algorithm

- **Step 3.** Perform eigenvalue decomposition on \mathbf{L} (or normalized \mathbf{L}) and use the first K eigenvectors to form a matrix \mathbf{Z}

$$\hat{\mathbf{L}} = \mathbf{V}\mathbf{\Sigma}\mathbf{V}^T, \quad \mathbf{Z} = [\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_K]^T \in \mathbb{R}^{K \times N}$$

- **Step 4.** Normalize the columns of \mathbf{Z} to unit L_2 norm , i.e.,

$$\mathbf{z}_i \leftarrow \mathbf{z}_i / \|\mathbf{z}_i\|, \quad i = 1, \dots, N$$

Spectral Clustering Algorithm

- **Step 3.** Perform eigenvalue decomposition on \mathbf{L} (or normalized \mathbf{L}) and use the first K eigenvectors to form a matrix \mathbf{Z}

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$$\mathbf{z}_i \leftarrow \mathbf{z}_i / \|\mathbf{z}_i\|, \quad i = 1, \dots, N$$

- **Step 5.** Perform K-means on $\{\mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_N\}$

Output: K of clusters of \mathbf{Z} or \mathbf{X}

Property of Graph Laplacian Matrix

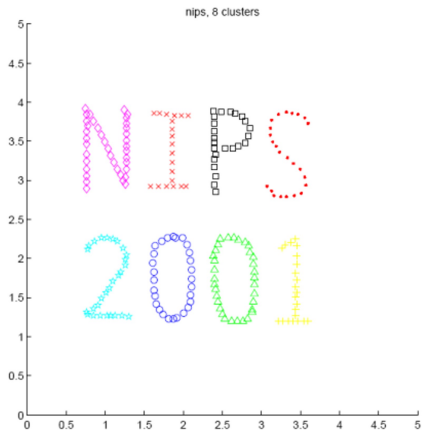
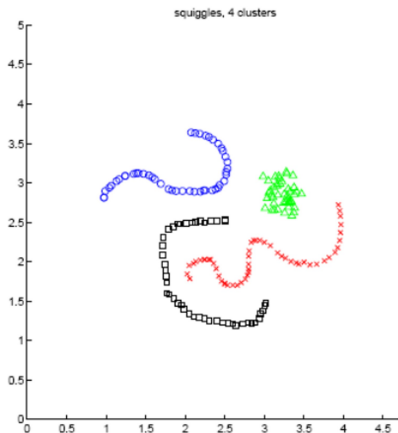
$$\mathbf{L} = \mathbf{D} - \mathbf{W} \quad \text{or} \quad \hat{\mathbf{L}} = \mathbf{I} - \mathbf{D}^{-1/2}\mathbf{W}\mathbf{D}^{-1/2}$$

- Symmetric and positive semi-definite
- The eigenvalues satisfy

$$0 = \lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \cdots \leq \lambda_{N-1} \leq \lambda_N$$

- If the number of zero eigenvalues is K , the graph has K connected components, corresponding to K clusters.

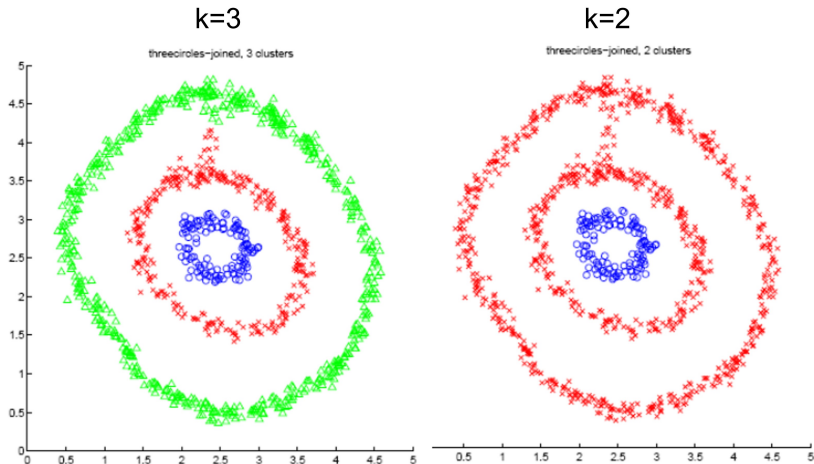
Examples of Spectral Clustering



Images from Ng et al. 2001

Examples of Spectral Clustering

- Influence of K

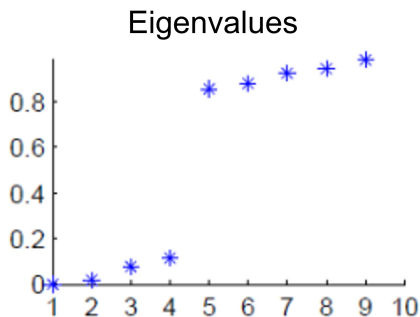


Images from Ng et al. 2001

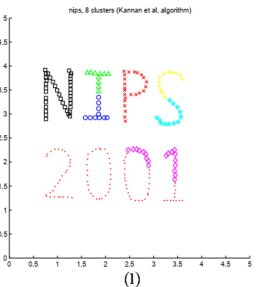
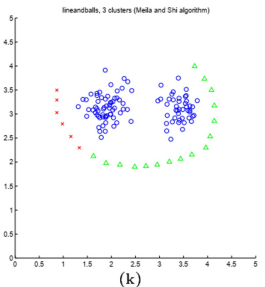
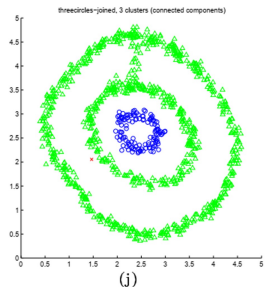
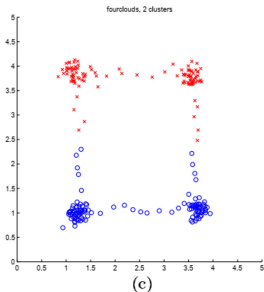
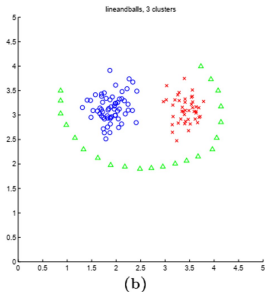
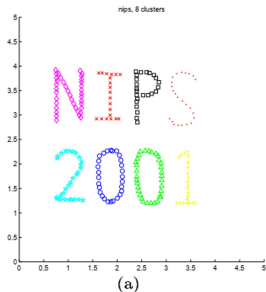
Determine K in Spectral Clustering

- Use the k that maximizes the eigengap (difference between consecutive eigenvalues)

$$\Delta_j = |\lambda_{j+1} - \lambda_j|, \quad K^* = \arg \max_j \Delta_j$$



More Examples of Spectral Clustering



Images from Ng et al. 2001

Characteristics of Spectral Clustering²

- High clustering accuracy in real applications
 - Often outperform k-means
- High computational cost, not applicable to big data
 - Space complexity: $O(N^2)$
 - Time complexity: $O(N^3)$

²More about spectral clustering can be found in: *A Tutorial on Spectral Clustering*.
Ulrike von Luxburg. 2007.

Characteristics of Spectral Clustering²

- High clustering accuracy in real applications
 - Often outperform k-means
- High computational cost, not applicable to big data
 - Space complexity: $O(N^2)$
 - Time complexity: $O(N^3)$
- Not easy to determine the similarity matrix
 - kNN , ϵ -neighborhood, Gaussian kernel, etc
 - Which method and what hyperparameter?

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Learning Outcomes

- Know the definitions of **cut** and **Ncut**
- Know the main steps of spectral clustering
- Know the property of **graph Laplacian** matrix
- Know the advantage and disadvantage of spectral clustering